ROBUST EVALUATION MATRIX

TOWARDS A MORE PRINCIPLED OFFLINE EXPLORATION OF INSTRUCTIONAL POLICIES

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- Large space of possible interventions. How do we choose what to try?

Can we tell how well an intervention will do without running it?

How can we determine what intervention is best?

• Can use simulated students!

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- Use student model to simulate an intervention.



Intervention

Intro to Calculus





Intervention







Intervention

Instructional Policy: Method of sequencing activities, possibly adaptive with respect to student state.

But what if the student model is inaccurate?

Simulate instructional policies on *several* student models!

Simulate instructional policies on *several* student models! Use many models we expect to be wrong, rather than using one model we hope to be right.







 $\frac{1}{4} < \frac{1}{3}$?



























	Policy 1	Policy 2	Policy 3
Student Model 1	V _{SM1} ,IP1	V _{SM1} ,IP2	V _{SM1} ,IP3
Student Model 2	V _{SM2} ,IP1	V _{SM2} ,IP2	V _{SM2} ,IP3
Student Model 3	V _{SM3} ,IP1	V _{SM3} ,IP2	V _{SM3} ,IP3
Student Model 4	V _{SM4} ,IP1	V _{SM4} ,IP2	V _{SM4} ,IP3

CASE STUDY: FRACTIONS TUTOR





	³ / ₆ +	2 8	= 18 =	3
2	Finally, redu	ce the su	um to lowest terms:	
	2 10 +	3 4	= 19 =	19 20

What goes wrong if we simulate on only a single student model?

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- Wanted to compare Adaptive Policy to a Baseline Policy (fixed, spiraling curriculum).
- Simulated both policies on G-SCOPE Model to predict posttest scores (out of 16 points).

	Baseline	Adaptive Policy
Simulated Results	5.9 ± 0.9	9.1 ± 0.8

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Simulated Results Experimental Results	$5.9 \pm 0.9 \\ 5.5 \pm 2.6$	$\begin{array}{c} 9.1\pm0.8\\ 4.9\pm1.8\end{array}$

• Used by Chi et al. (2011) and Rowe et al. (2014) in educational settings.

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- If each policy is only simulated on the student model that was used to derive it, a sub-optimal policy might be predicted to be better than the optimal policy under the true student model (Mandel et al., 2014).

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- If each policy is only simulated on the student model that was used to derive it, a sub-optimal policy might be predicted to be better than the optimal policy under the true student model (Mandel et al., 2014).
 - Even with an infinite amount of data!

	Baseline	Adaptive Policy	
G-SCOPE Model	5.9 ± 0.9	9.1 ± 0.8	

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	Baseline	Adaptive Policy	
G-SCOPE Model	5.9 ± 0.9	9.1 ± 0.8	
Bayesian Knowledge Tracing Model	6.5 ± 0.8	7.0 ± 1.0	
Deep Knowledge Tracing Model	9.9 ± 1.5	8.6 ± 2.1	

Dasetine	Adaptive Policy	Awesome Policy
G-SCOPE Model 5.9 ± 0.9 Bayesian Knowledge Tracing Model 6.5 ± 0.8 Doop Knowledge Tracing Model 0.0 ± 15	9.1 ± 0.8 7.0 ± 1.0	16 16 16

See paper for another retrospective analysis of prior work (Rafferty et al., 2015) showing REM can be used:

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- \cdot to find good policies, robust to the choice of the model
- to spot bad policies that single model simulation could not catch

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- Showed retrospective analysis of how REM could have been used to inform experiment.
- Next Step: Close the loop.

Use many models we expect to be wrong, rather than using one model we hope to be right.

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- Can have very high variance when policy is different from prior data.
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 - · 20 sequential decisions \Rightarrow need over 2²⁰ students
 - 50 sequential decisions \Rightarrow need over 2⁵⁰ students!